

## 1 Bayesian Estimation of Variance of a Gaussian Process

Consider a Gaussian distribution with mean  $\mu$  and variance  $X$  to be the mathematical model of a physical process/system. Specifically, an output quantity of interest  $Y$  follows the Gaussian distribution  $Y \sim N(\mu, X)$  or, equivalently, the measure of the uncertainty in  $y$  given that  $X = \sigma^2$  is given by the PDF

$$p(y | x, \mu, I) = \frac{1}{\sqrt{2\pi X}} \exp\left[-\frac{1}{2X}(y - \mu)^2\right] \quad (1)$$

Given a set of independent observations/data  $D \equiv (\hat{Y}_1, \hat{Y}_2, \dots, \hat{Y}_N) \equiv \{\hat{Y}_k\}_{1 \rightarrow N}$ , we are interesting in updating the uncertainty in the variance  $X$  of the model. It is assumed that the value of the mean  $\mu$  is known. For simplicity we use  $x = \sigma^2$  to denote the possible values of the uncertain variable  $X$ . Assume a uniform prior for  $\sigma^2$  and derive the expressions for the

1. Posterior PDF  $p(\sigma^2 | D, \mu, I)$ . Note that the posterior PDF follows a inverse gamma distribution  $IG(\alpha, \beta)$ . What are the values of  $\alpha$  and  $\beta$ ? (Already done in Homework 1)
2. The function  $L(\sigma^2) = -\ln p(\sigma^2 | D, \mu, I)$
3. The MPV (or best estimate)  $\hat{\sigma}^2$  of  $\sigma^2$
4. The uncertainty of  $\sigma^2$
5. Retain up to the quadratic terms in the Taylor series expansion of  $L(\sigma^2)$  about the most probable value  $\hat{\sigma}^2$  and derive the Gaussian asymptotic approximation for the posterior PDF of  $p(\sigma^2 | \{\hat{Y}_k\}_{1 \rightarrow N}, \mu, I)$
6. [THIS QUESTION WAS NOT COVERED IN CLASS] Compare the posterior PDF with the asymptotic Gaussian posterior PDF for the following values of  $N = 1, 2, 3, 4, 10, 100, 1000$ . To facilitate comparisons, plot the two posterior PDFs (exact and asymptotic) so that the maximum value of each equals unity.

Prior PDF: The uniform PDF for  $\sigma^2$  is given by

$$p(\sigma^2 | \mu, I) = \begin{cases} \sigma_{\max}^{-2}, & \sigma^2 \in [0, \sigma_{\max}^2] \\ 0 & \text{otherwise} \end{cases} \quad (2)$$

Posterior PDF: Using Bayes' theorem, the inference about the value  $\sigma^2$  given the data  $D$ , the mean value  $\mu$  and the information  $I$  ( $I$  includes the selection of the Gaussian model) is expressed by the posterior PDF

$$p(\sigma^2 | D, \mu, I) \propto p(D | \sigma^2, \mu, I) p(\sigma^2 | \mu, I) \quad (3)$$

Likelihood: The likelihood has already been evaluated in Lecture Notes 2 in the form

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$$\begin{aligned}
 p(D | \sigma^2, \mu, I) &= p(\{\hat{Y}_k\}_{1 \rightarrow N} | \sigma^2, \mu, I) = \prod_{k=1}^N p(\hat{Y}_k | \sigma^2, \mu, I) \\
 &= \prod_{k=1}^N \frac{1}{\sqrt{2\pi}\sigma} \exp\left[-\frac{1}{2\sigma^2}(\hat{Y}_k - \mu)^2\right]
 \end{aligned} \tag{4}$$

Estimation of Posterior PDF: Using (4) to replace the first factor in the right hand side (RHS) of (3) and the uniform prior PDF (2), the posterior PDF of the uncertain parameter  $\sigma^2$  given the mean value  $\mu$  takes the form

$$\begin{aligned}
 p(\sigma^2 | D, \mu, I) &\propto \prod_{k=1}^N \frac{1}{\sqrt{2\pi}\sigma} \exp\left[-\frac{1}{2\sigma^2}(\hat{Y}_k - \mu)^2\right] \\
 &\propto \frac{1}{\sigma^N} \exp\left[-\frac{1}{2\sigma^2} \sum_{k=1}^N (\hat{Y}_k - \mu)^2\right]
 \end{aligned} \tag{5}$$

Note that the distribution of the parameter  $\sigma^2$  is not Gaussian. In fact, it has been shown in Homework 1 that it follows a inverse gamma distribution.

Most Probable Value (MPV) or Best Estimate: The function  $L(\sigma^2)$ , defined in theory as the minus the logarithm of the posterior PDF of  $\sigma^2$ , is given by

$$L(\sigma^2) = -\log p(\sigma^2 | \{\hat{Y}_k\}_{1 \rightarrow N}, \mu, I) = \frac{N}{2} \log \sigma^2 + \frac{1}{2\sigma^2} \sum_{k=1}^N (\hat{Y}_k - \mu)^2 + \text{constant} \tag{6}$$

The MPV of  $\hat{\sigma}^2$  maximize the posterior PDF or, equivalently, minimize  $L(\sigma^2)$ . It satisfies the condition

$$\left. \frac{\partial L}{\partial \sigma^2} \right|_{\sigma^2 = \hat{\sigma}^2} = \left[ \frac{N}{2\sigma^2} - \frac{1}{2\sigma^4} \sum_{k=1}^N (\hat{Y}_k - \mu)^2 \right]_{\sigma^2 = \hat{\sigma}^2} = \frac{1}{2\hat{\sigma}^2} \left[ N - \frac{1}{\hat{\sigma}^2} \sum_{k=1}^N (\hat{Y}_k - \mu)^2 \right] = 0$$

The solution for the MPV  $\hat{\sigma}^2$  is readily obtained as

$$\hat{\sigma}^2 = \frac{1}{N} \sum_{k=1}^N (\hat{Y}_k - \mu)^2 \tag{7}$$

which is the arithmetic variance of the measurements  $(\hat{Y}_1, \hat{Y}_2, \dots, \hat{Y}_N)$ .

Uncertainty in Model Parameters: The uncertainty in the value of the model parameters  $\sigma^2$  given the value of the mean  $\mu$  is characterized by the Hessian of the function  $L(\sigma^2)$  evaluated at the MPV  $\hat{\sigma}^2$ . The Hessian is given by

$$\left. \frac{\partial^2 L}{\partial (\sigma^2)^2} \right|_{\sigma^2 = \hat{\sigma}^2} = -\frac{N}{2\hat{\sigma}^4} + \frac{2\hat{\sigma}^2}{2\hat{\sigma}^8} \sum_{k=1}^N (\hat{Y}_k - \mu)^2 = -\frac{N}{2\hat{\sigma}^4} + \frac{\hat{\sigma}^2}{\hat{\sigma}^8} N\hat{\sigma}^2 = -\frac{N}{2\hat{\sigma}^4} + \frac{N}{\hat{\sigma}^4} = \frac{N}{2\hat{\sigma}^4}$$

The measure of the uncertainty, provided by the square root of the inverse of the Hessian of  $L(\sigma^2)$  evaluated at the most probable value  $\hat{\sigma}^2$ , is given by

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$$\sqrt{S} = \left( \frac{d^2 L}{d(\sigma^2)^2} \Big|_{\sigma^2 = \hat{\sigma}^2} \right)^{-1/2} = \frac{\sqrt{2} \hat{\sigma}^2}{\sqrt{N}}$$

Given the MPV  $\hat{\sigma}^2$  and the uncertainty index  $\sqrt{S}$  we can write a measure of the uncertainty interval of  $\sigma^2$  in the form

$$\hat{\sigma}^2 \pm \sqrt{S} = \hat{\sigma}^2 \pm \frac{\sqrt{2} \hat{\sigma}^2}{\sqrt{N}} \quad (8)$$

Asymptotic Posterior PDF: Following the theoretical result for the Bayesian Central Limit Theorem and using the MPV  $\hat{\sigma}^2$  and the uncertainty index  $S$ , the posterior PDF follows asymptotically for large number of data  $N$  the Gaussian distribution

$$p(\sigma^2 | D, \mu, I) = \frac{\sqrt{N}}{\sqrt{2\pi} \sqrt{2} \hat{\sigma}^2} \exp \left[ -\frac{N}{4\hat{\sigma}^4} (\sigma^2 - \hat{\sigma}^2)^2 \right] \quad (9)$$

[THIS QUESTION WAS NOT COVERED IN CLASS] Figure 1 shows the evolution of the posterior PDF  $p(\sigma^2 | D, \mu, I)$  (the posterior uncertainty in  $\sigma^2$ ) as a function of the number of data. Note that data affects the values of  $\hat{\sigma}^2$  and  $S$ , while the posterior PDF in this case is asymptotically approaching a Gaussian distribution  $N(\hat{\sigma}^2, 2\hat{\sigma}^4 / N)$  for large values of  $N$ .