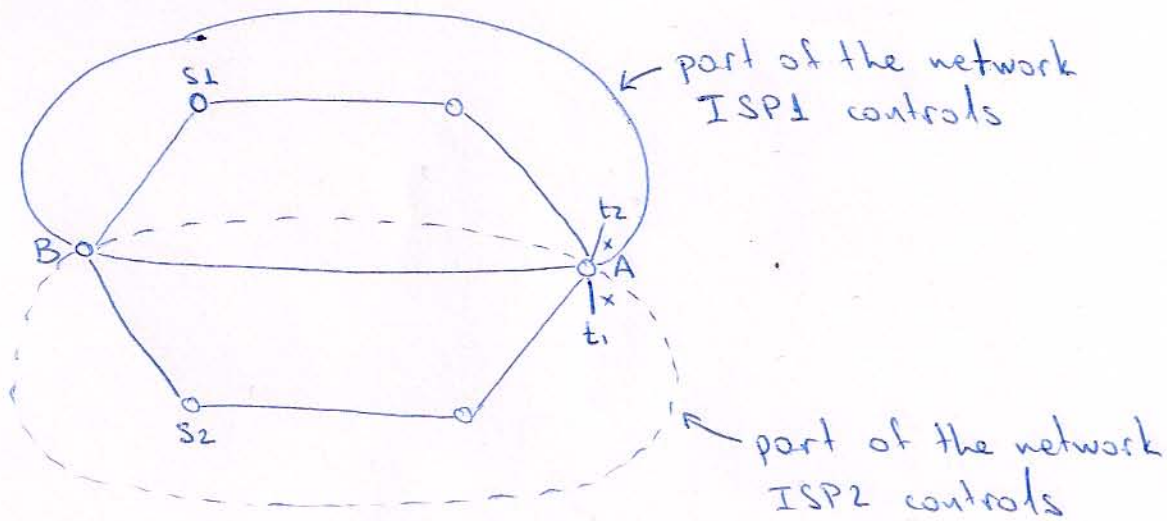


Όνομα: George Kyriakou.

ISP routing problem → ISP competition ⇒ prisoner's dilemma
→ ISPs cooperate



goals:

ISP1 wants to make a transfer from S_1 to t_1

ISP2 wants to make a transfer from S_2 to t_2

↳ transfer cost from A to t_1 and t_2 is considered ∞

Strategy: will they complete the transfer through point A or point B?

The cost of a transfer is equal to the required number of hops.

Each ISP wants to create the minimum possible traffic within his network. As a result, ISP1 wants to transfer through B (cost 1 for his network) and ISP2 wants to transfer through node A for the same reasons.

social optimum

	A	B
A	(2, 2)	(5, 1)
B	(5, 1)	(4, 4)

N.E. (each ISP causes cost 1 to himself and 3 to the other)

(2)

Obviously PoA = 2

► Exercise

N ice-cream sellers must be placed along a beach of length 1:



The bigger the distance from his neighbors, the greater the profit.

$x_i \in [0, 1]$: each ice-cream seller's placement

utility function: $u_i(x_i) = \frac{x_{i+1} - x_{i-1}}{2}$ } where x_{i+1} and x_{i-1} are his closest neighbors to his right and left respectively

$u_i(x_i) = \frac{1}{2} [(x_{i+1} - x_i) + (x_i - x_{i-1})]$

$x_0 = 0$ & $x_{N+1} = 1$ are the ice-cream sellers sitting on 0 and 1 respectively and cannot be moved

Can you prove that:

i) if $N=2$: $(x_1^*, x_2^*) = (1/2, 1/2)$ and $\begin{cases} u_1(x_1) = \frac{x_2}{2} \\ u_2(x_2) = \frac{1-x_1}{2} \end{cases}$

ii) if $N=3$: \nexists Nash Equilibrium

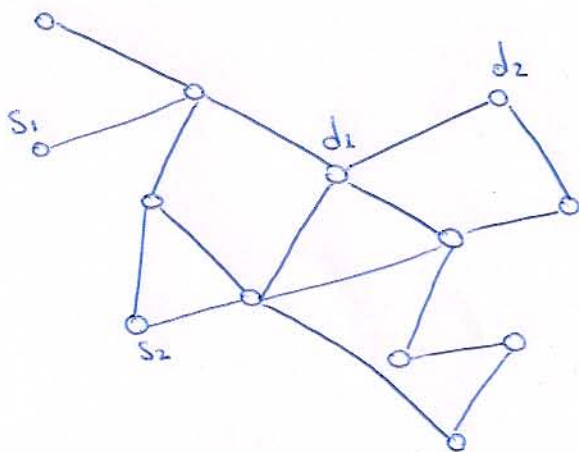
iii) if the ice-cream sellers were placed on a circle, the Nash Equilibrium would be the state when they had equal distances between them

Second Part

- Routing Games
- Congestion Games
- Scheduling Games

► Routing Games

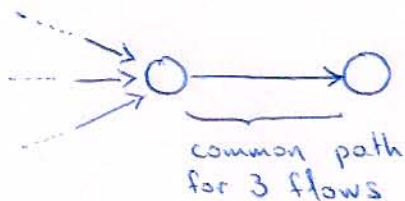
Given a network:



Each player wants to transfer his information from his source (s_i) to his destination (d_i).

When there are common links in the paths

e.g.



all flows/players affect each other.

- There is a load dependent cost (i.e. latency) function at each link.

As a result, the more traffic on a link, the longer the delay.

There are two types of links:

- i) Splittable (non-atomic): each link can be used by more than one flow at the same time
- ii) Unsplittable (atomic): each link can be used only by one flow at a time

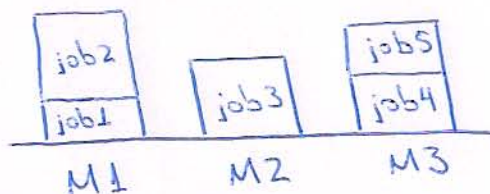
Example

N jobs (players): each job i has a weight (i.e. computational cost) $w_i \geq \epsilon$

M machines ($N \gg M$): each machine j has computational power $s_j \geq \epsilon$

By $a_i = j$ we mean that job i is assigned to machine j .

Let's assume the following jobs assignment:



If L_j is the load at the machine M_j :

$$L_j(\underline{a}) = \frac{\sum_{i: a_i=j} w_i}{s_j}$$

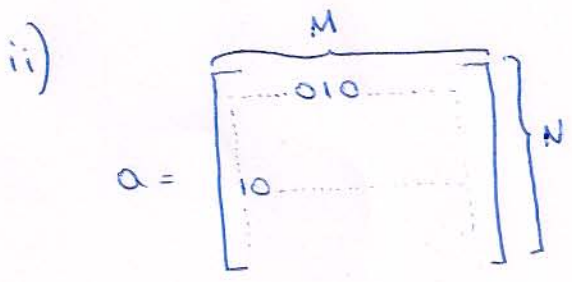
\rightarrow the sum of weights of all jobs assigned to machine M_j
 \rightarrow computational power of machine M_j

Vector \underline{a} describes the way jobs are assigned to machines. It can have various forms:

e.g.

i) $\underline{a} = (a_1, a_2, \dots, a_N)$

\hookrightarrow its value represents the machine that this job is assigned to



If $a_{ij} = 1$, job i is assigned to machine j .
 Since each job can be assigned to only one machine (i.e. jobs can't be split) each line can have only one '1'

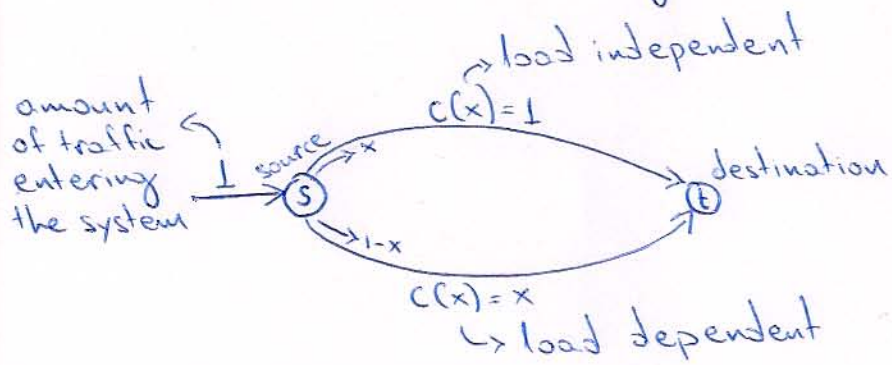
Our goal is to minimize the overall load:

$$\text{minimize } \sum_{j=1}^M L_j(\underline{a}) = \text{minimize } \sum_{j=1}^M \left(\frac{1}{s_j} \cdot \sum_{i: a_i=j} w_i \right)$$

practically $\frac{w_i}{s_j}$ represents the time machine j needs to complete job i

Example (Pigou 1920)

Given the following network with splittable links:



→ the traffic entering the system (here is 1) is split into two flows: "x" and "1-x"

→ each link has a different cost function $c(x)$ (representing cost per traffic unit)

global optimum: minimize $x \cdot 1 + (1-x) \cdot (1-x)$ ①

$$x \cdot 1 + (1-x)^2 = x + 1 - 2x + x^2 = x^2 - x + 1$$

$$(x^2 - x + 1)' = 2x - 1$$

$$2x - 1 = 0 \Rightarrow x^* = \frac{1}{2} \text{ ②}$$

As a result, the delay in the social optimum

$$\text{is (from ①, ②): } \frac{1}{2} \cdot 1 + (1 - \frac{1}{2})(1 - \frac{1}{2}) \Rightarrow D_{so}^* = \frac{3}{4}$$

If everyone chose selfish, all players would choose the bottom link. This would cause

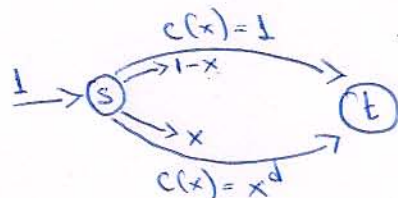
a delay:

$0 \cdot 1 + 1 \cdot 1 = 1$, since in the Nash Equilibrium $x_{N.E.} = 0$

$$\text{Price of Anarchy} = \frac{\text{delay in N.E.}}{\text{delay in S.O.}} = \frac{1}{3/4} = \frac{4}{3}$$

* If the cost function is linearly dependent on the load of the link, the Price of Anarchy will not exceed $4/3$, no matter the size of the network, the number of players, latency, etc.

If we have the same problem but without a linear cost function:



global optimum: minimize $(1-x) \cdot 1 + x \cdot x^d = 1-x + x^{d+1}$ ①

$$\frac{d(1-x+x^{d+1})}{dx} = 0 \Rightarrow x^*(d) = \frac{1}{(d+1)^{1/d}} \quad \text{②}$$

Nash Equilibrium: $x_{N.E.} = 1 \Rightarrow \text{delay} = 0 \cdot 1 + 1 \cdot 1^d = 1$

$$\lim_{d \rightarrow +\infty} x^*(d) = \lim_{d \rightarrow +\infty} \frac{1}{(d+1)^{1/d}} \stackrel{a = e^{\log a}}{=} \lim_{d \rightarrow +\infty} \frac{1}{e^{1/d \cdot \log(d+1)}} \quad (3)$$

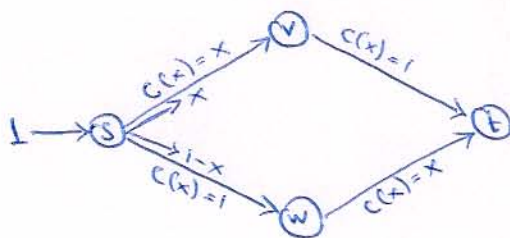
but $\frac{\log(d+1)}{d} \xrightarrow{d \rightarrow +\infty} 0 \quad (4)$

$\begin{matrix} (3) \\ (4) \end{matrix} \Rightarrow \lim_{d \rightarrow +\infty} x^*(d) = \frac{1}{e^0} = 1 \quad (5)$

$\begin{matrix} (1) \\ (2) \end{matrix} \Rightarrow 1 - x + \frac{1}{(d+1)^{1/d}} \xrightarrow{d \rightarrow +\infty} 1 - 1 + 0 = 0$
 delay at S.O.

So, $P_0A = \frac{\text{delay at N.E.}}{\text{delay at S.O.}} = \frac{1}{0} \rightarrow +\infty$

● Braess Paradox



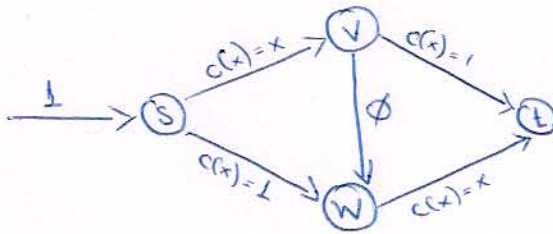
Social Optimum: minimize $x \cdot (x+1) + (1-x)(1+x) = x^2 + x + 1 + 1 - x - x - x + x^2 = 2x^2 - 2x + 2$

$\frac{d(2x^2 - 2x + 2)}{dx} = 0 \Rightarrow 4x - 2 = 0 \Rightarrow x^* = 1/2$

$$\text{delay}_{\text{s.o.}} = 2 \cdot \left(\frac{1}{2}\right)^2 - 2 \cdot \left(\frac{1}{2}\right) + 2 = \frac{3}{2}$$

Nash Equilibrium: $x_{\text{N.E.}} = \frac{1}{2} = x^* \Rightarrow \underline{P_{\text{O.A.}} = 1}$

However, if we add a link 'v → w' with null cost:



we now have three paths with the following costs:

$$\left. \begin{array}{l} S \rightarrow v \rightarrow t: x + 1 \\ S \rightarrow w \rightarrow t: x + 1 \\ S \rightarrow v \rightarrow w \rightarrow t: 2x \end{array} \right\} \begin{array}{l} \text{since } x \leq 1 \Rightarrow 2x \leq x + 1 \\ \text{all selfish players in N.E.} \\ \text{will choose the third path} \end{array}$$

$$\left. \begin{array}{l} \text{As a result, } \text{delay}_{\text{N.E.}} = 1 \cdot 1 + 0 \cdot 1 + 1 \cdot 1 = 2 \\ \text{(Social Optimum will remain the same)} \end{array} \right\} P_{\text{O.A.}} = \frac{2}{\frac{3}{2}} = \frac{4}{3}$$

▣ Graphs

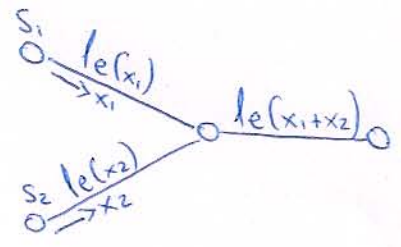
$$G = (V, E)$$

\downarrow \downarrow \searrow
 graph vertex edges

k players want to transmit from source (s_i) to destination (t_i) over a given network (graph)

each player i has a demand function r_i

$\forall e \in E : l_e(x) : \mathbb{R}^+ \rightarrow \mathbb{R}^+$
↳ latency function of an edge, depends on load
↳ \exists derivative, non-decreasing



P_i : group of paths that player i uses

$$P = \bigcup_i P_i$$

f_p : flow over a path p }
 f_e : flows over an edge e } $f_e = \sum_{p: e \in p} f_p$

$$r_i = \sum_{p \in P_i} f_p \Rightarrow \sum_{p \in P_i} \frac{f_p}{r_i} = 1$$

latency of a path: $l_p(f) = \sum_{e \in p} l_e(f_e)$

Overall Cost: $C(f) = \sum_{p \in P} f_p \cdot l_p(f_p) = \sum_{e \in E} \underbrace{f_e}_{\text{traffic}} \cdot \underbrace{l_e(f_e)}_{\text{cost per traffic unit}}$

For a single player i : $C_i(f) = \sum_{p \in P_i} f_p \cdot l_p(f_p) = \sum_{e \in P_i} f_e \cdot l_e(f_e)$

Strategy: How will a player split his flow

- i) Atomic Routing (unsplittable): $\{p_1, p_2, \dots, p_{|P_i|}\}$
- ii) Non-atomic Routing (splittable): $\{f_{p_1}, f_{p_2}, \dots, f_{p_{|P_i|}}\}$