Title goes here

Author Name

Email: me@uth.gr

Abstract

Abstract goes here.

I. INTRODUCTION

...text.

II. SYSTEM MODEL

Math formulas:

$$\frac{\partial F(\mathbf{U}, \mathbf{p})}{\partial p_i} = \frac{w_i}{p_i} - \sum_{j \neq i}^{K} w_j \frac{\mathbf{u}_j^H \mathbf{R}_i \mathbf{u}_j}{I_j + \sigma^2},$$

Reference to [1].

Figure (at top of page):

Table:

variable	value
A	12
B	4
C	8

REFERENCES

[1] G. J. Foschini and Z. Miljanic, "A simple distributed autonomous power control algorithm and its convergence," *IEEE Transactions on Vehicular Technology* vol. 42, no. 4, pp. 641-646, Nov. 1993.
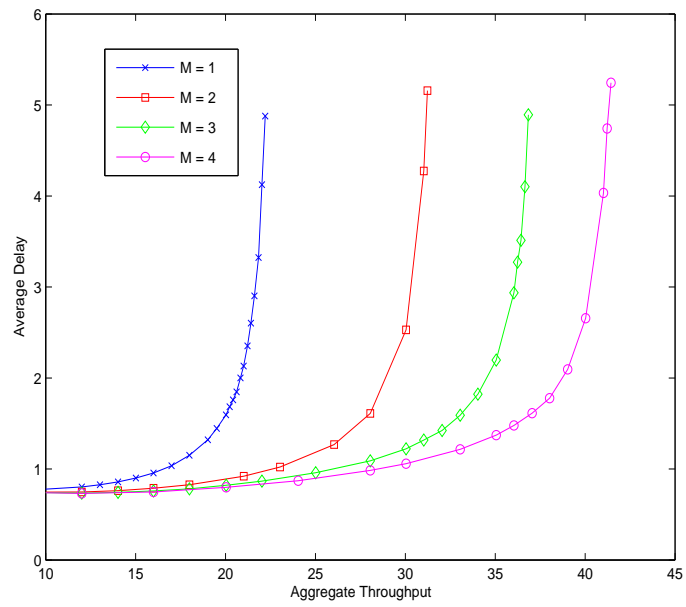
Fig. 1.   Figure caption.